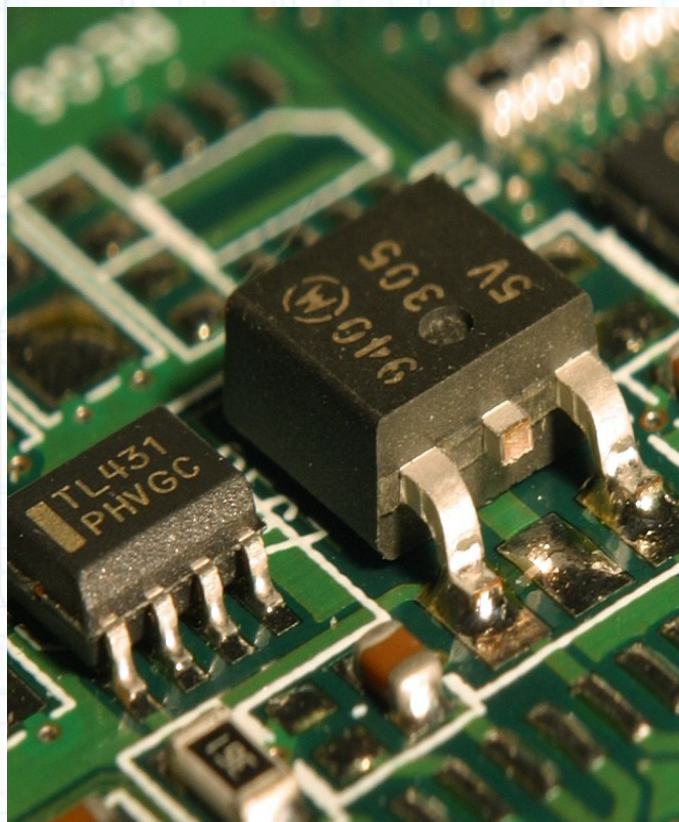


**Need for Speed:  
Process Agnostic Library  
Migration Automation**

*Joseph Murray*

*Lijun Li*

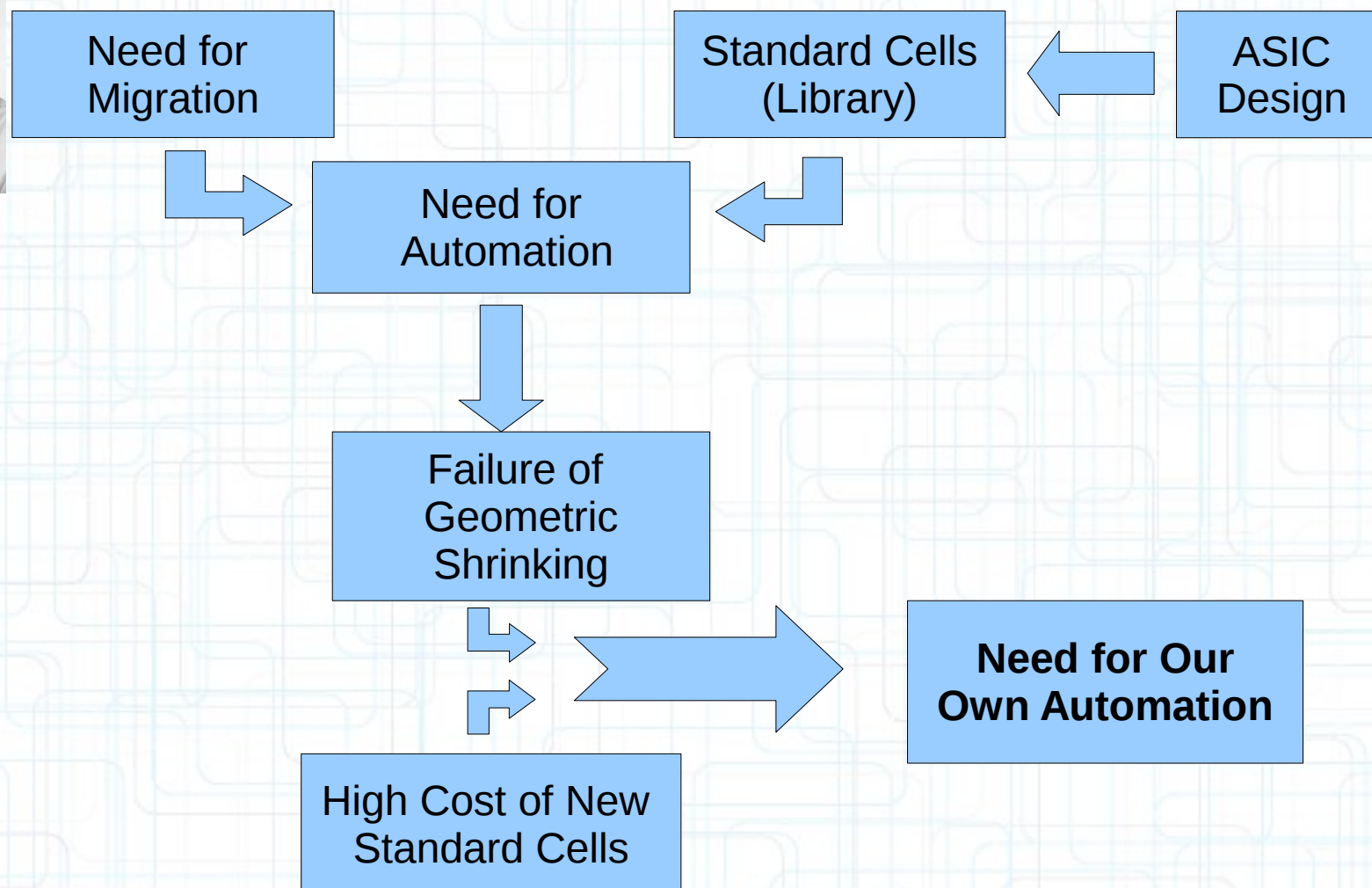
# Outline



- Motivation
- Approach
  - PyCell Studio
  - Cadence SKILL
- Comparison
- Summary



# Why Process Agnostic Migration Automation



## Project Purpose:

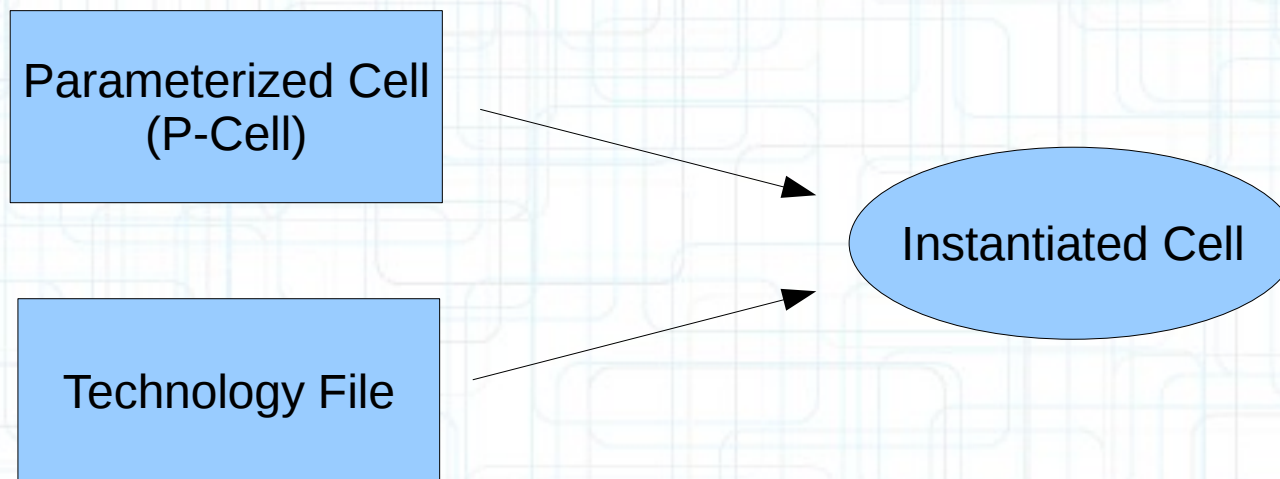
1. Demonstrate the concept
2. Evaluation

# PyCell Studio: Design Overview

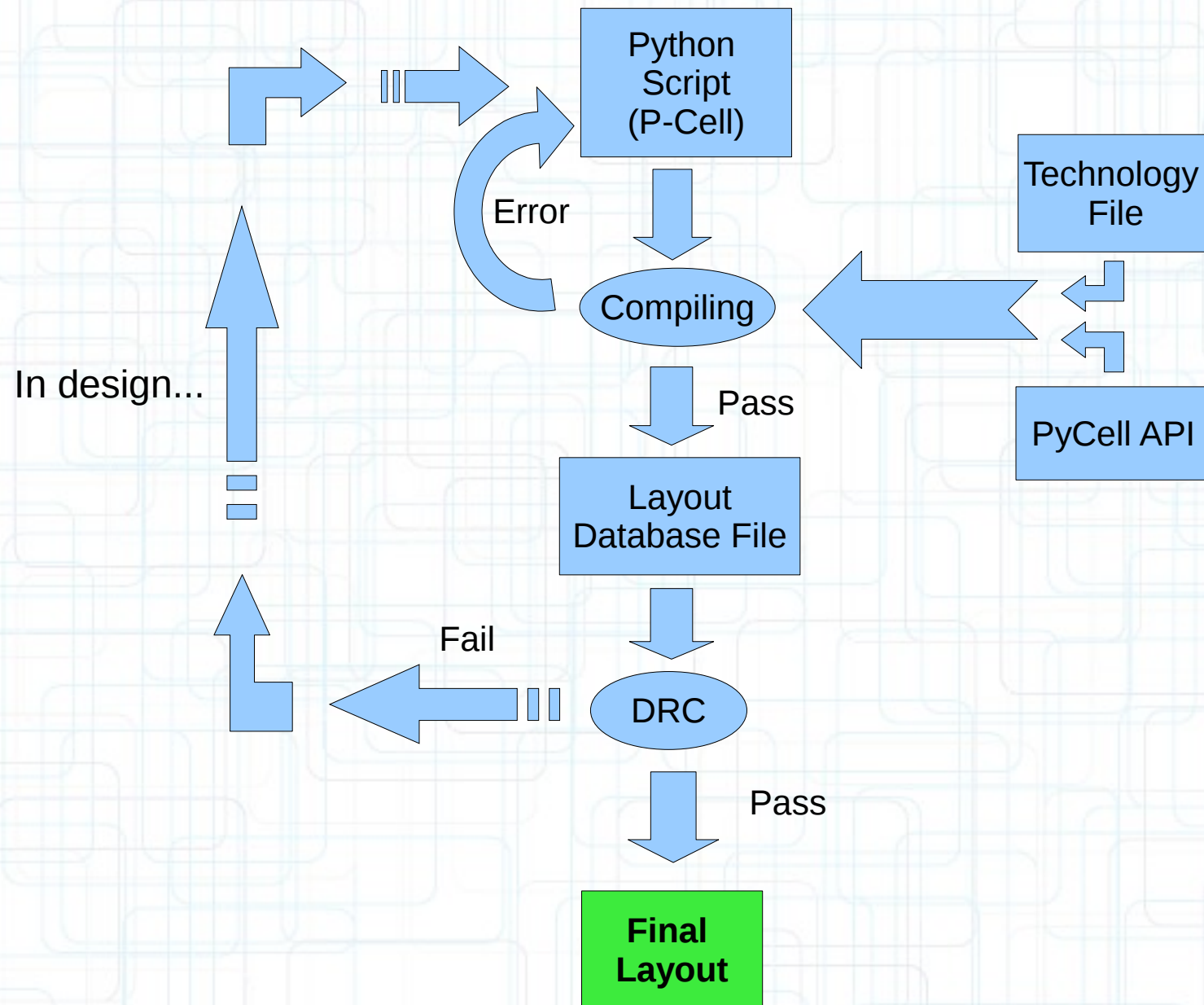
PyCell:

- ◆ Based on Python
- ◆ Free to use and multiplatform
- ◆ Open Access database
- ◆ Geared towards parameterized cell design
- ◆ **Our home-made PyCell recipe @ ECE Wiki**

Parameterized Cell Methodology:

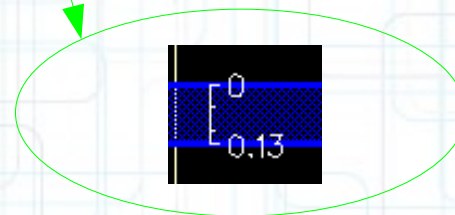
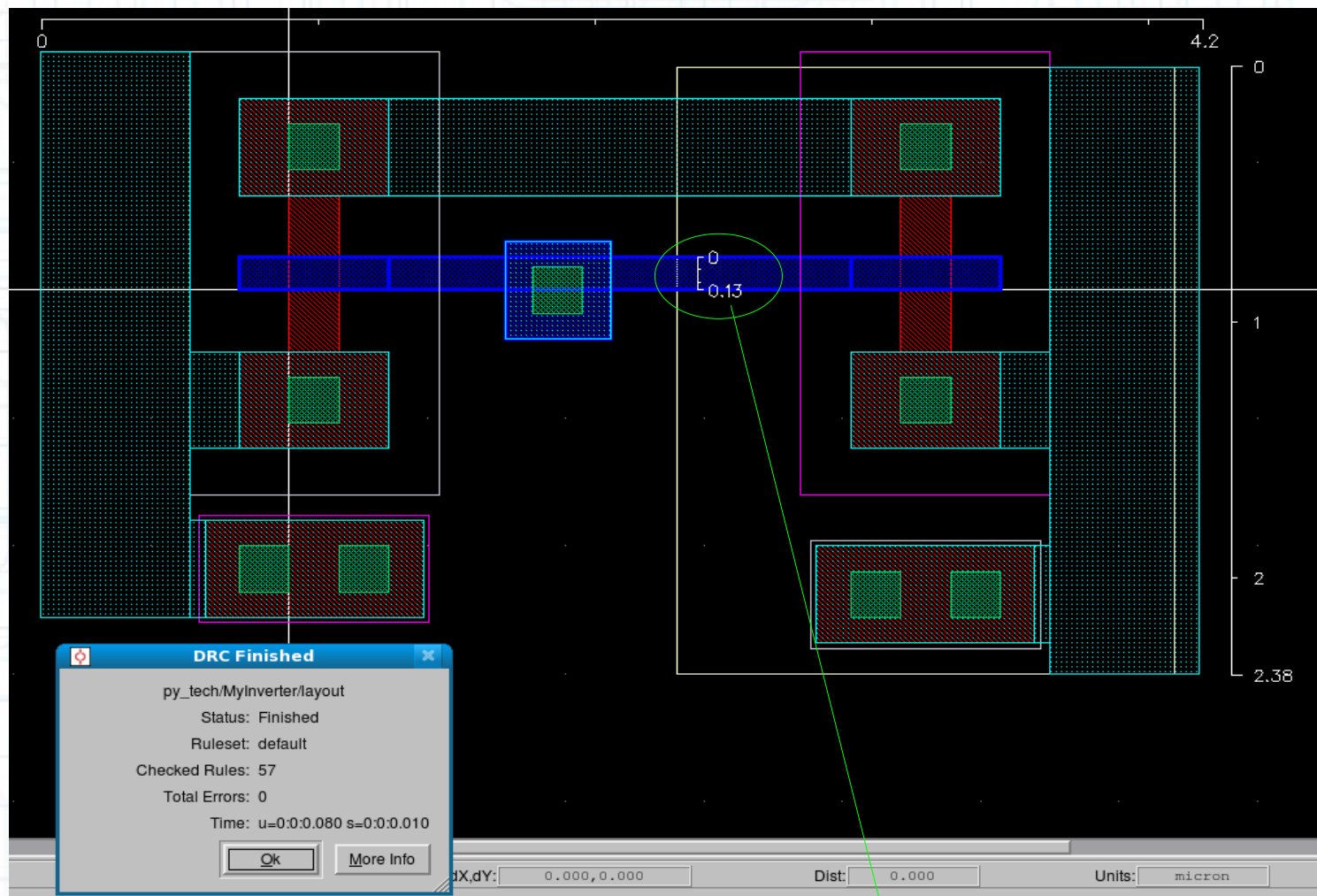


# PyCell Studio: Methodology

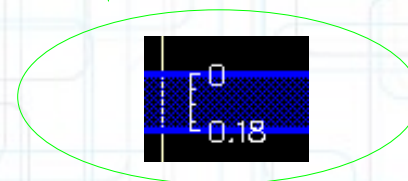
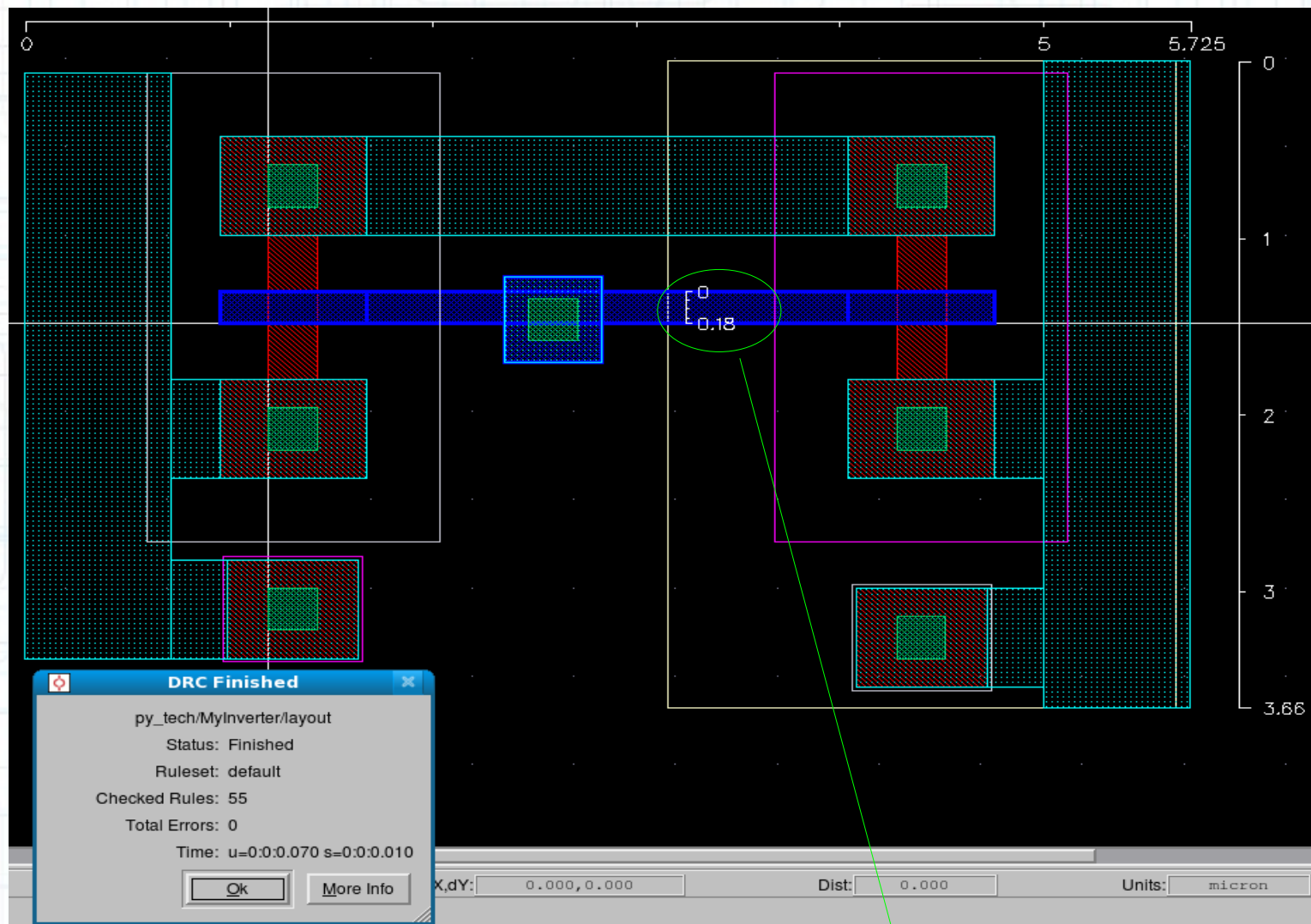




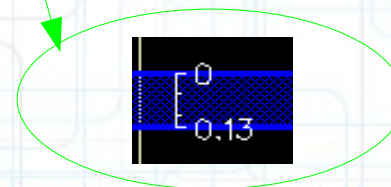
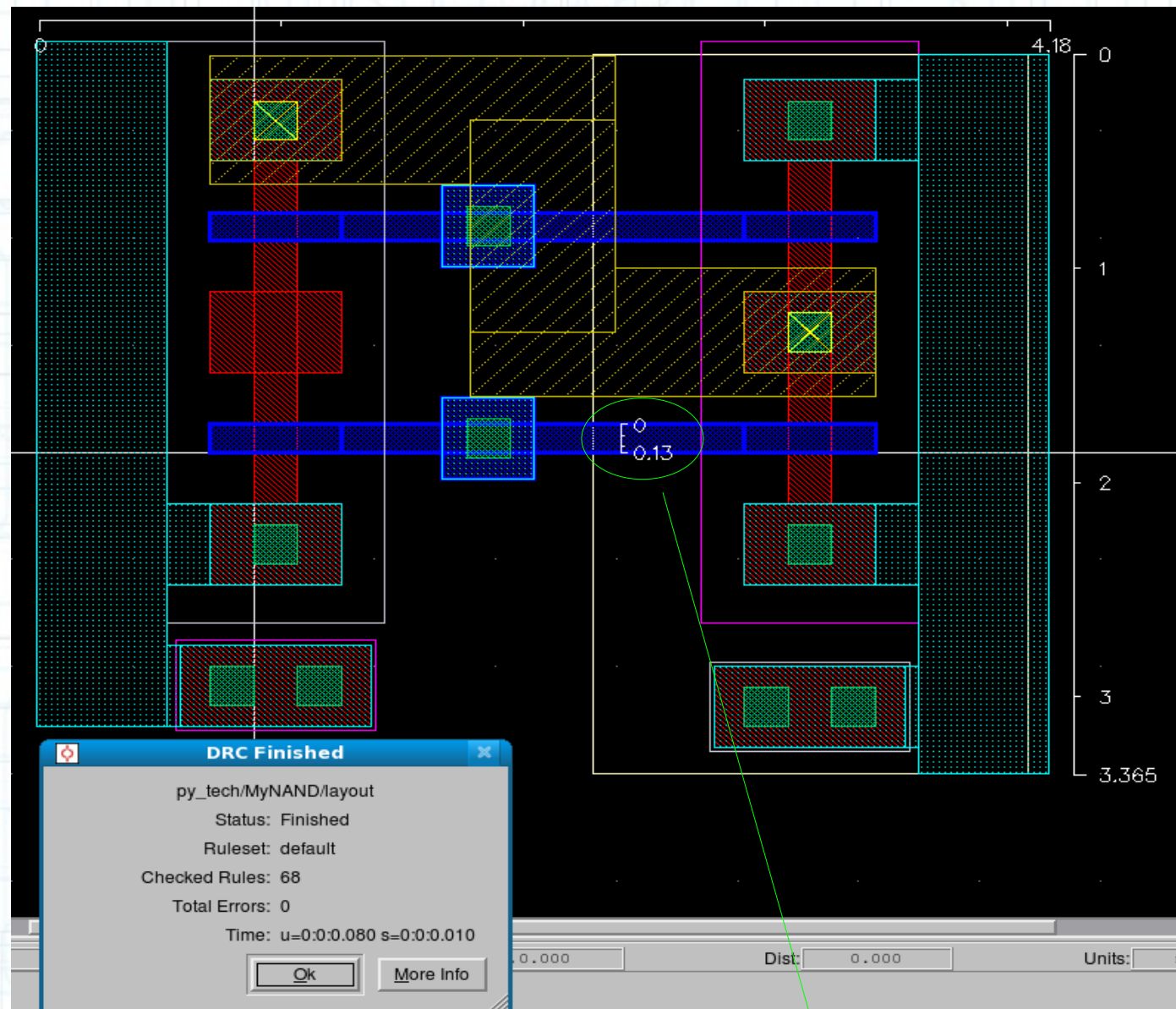
# PyCell Studio: Inverter @130nm



# PyCell Studio: Inverter @180nm

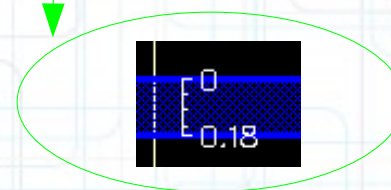
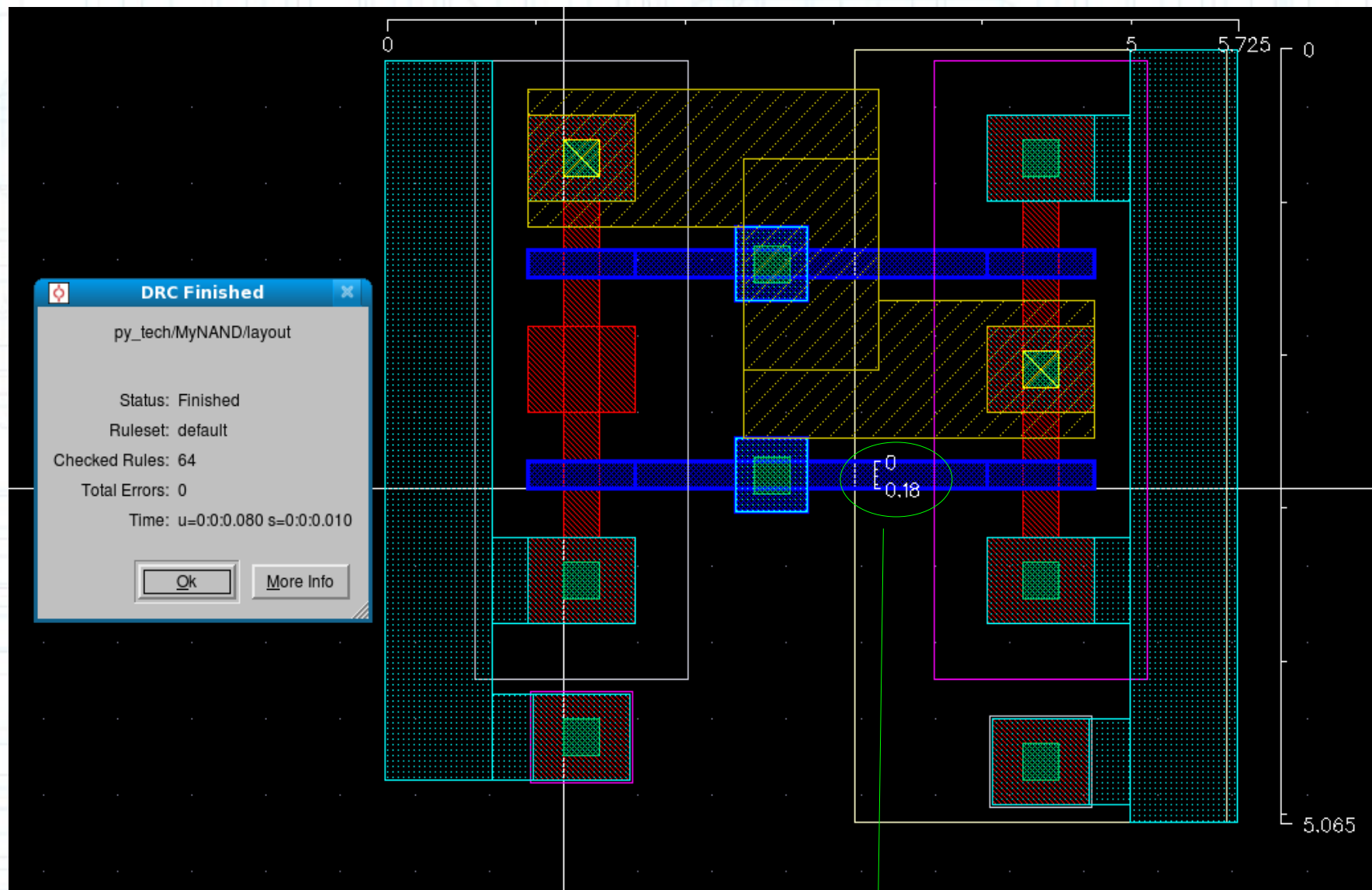


# PyCell Studio: NAND @130nm





# PyCell Studio: NAND @180nm



# PyCell Studio: Pros & Cons

## Pros

- DRC automatically met
- Relatively simple design (almost no more than geometry)

```

229 # that pEnc belongs to a different class from DfEnc which Group class belong to.
230 # and these two classes are not communicative so it is not double to directly assign the value
231
232 # now create the gate contact
233 gateContact=Contact(self.gateLayer, self.metalLayer,"PDK")
234 # as input of inverter, use default contact width
235 # the cords of gateContact is still floating
236
237 pgroup.add(pEncPimp) # add layer pImp into pgroup
238 fplPlaceGateContact, WEST, pgroup)
239 pgroupContactDist = pgroup.getBoundingBox().left - gateContact.getBoundingBox().right # measure the position of gateContact w.r.t pgroup
240 fplPlaceGateContact(EAST, ngroup)
241 ngroupContactDist = gateContact.getBoundingBox().left - ngroup.getBoundingBox().right # measure the position of gateContact w.r.t ngroup
242 gateContactWidth = gateContact.getBoundingBox().right - gateContact.getBoundingBox().left
243 # till now gateContact has been put to the east of nmos
244
245 # now place ntap
246 fplPlaceIntapGroup, SOUTH, pgroup)
247 pgroup.add(IntapGroup)
248 pEncMcp = fplPlaceEnclosureRect(pgroup, (Layer("well")))
249 pEncMcpWell = Rect(Layer("well"), pEncMcp.getBoundingBox()) # form well
250 pgroup.add(pEncMcpWell)
251 pEncMcp.destroy()
252 pmoveDist = ngroup.getBoundingBox().right + ngroupContactDist + gateContactWidth + pgroupContactDist - pEncMcpWell.getBoundingBox().left
253 pgroup.moveTowards(EAST, pmoveDist) # move the pms to a proper position
254
255 polyGap = Rect(self.gateLayer, Box(pgateRect.getBoundingBox().right, ngateRect.getBoundingBox().bottom, pgateRect.getBoundingBox().left, pgateRect.get
256 BBox().top))
257 # draw poly to fill the gap between nmos and pmos gates
258
259 npowerMetal = Rect(self.metalLayer, Box(0, 0, self.powerMetalWidth, (pEncMcpWell.getBoundingBox().top-pgateRect.getBoundingBox().bottom))) # draw n
260 as power metal layer (VDD), but the code are still floating
261 ppowerMetal = Rect(self.metalLayer, Box(0, 0, self.powerMetalWidth, (pEncMcpWell.getBoundingBox().top-pEncMcpWell.getBoundingBox().bottom))) #
262 draw pmos power metal layer (VDD)
263
264 prMetal = self.tech.getPhysicalRule("minimumSpacing", Layer("metal")) # get the minimum spacing of metal
265 npowerMetal.setRight(pgateRect.getBoundingBox().left - prMetal.value)
266 npowerMetal.setLeft(pgateRect.getBoundingBox().left - prMetal.value)
267 npowerMetal.setTop(pgateRect.getBoundingBox().top)
268 npowerMetal.setBottom(pgateRect.getBoundingBox().bottom)
269 ppowerMetal.setLeft(pgateRect.getBoundingBox().right + prMetal.value)
270 ppowerMetal.setRight(pgateRect.getBoundingBox().right + prMetal.value + self.powerMetalWidth)
271 ppowerMetal.setTop(pEncMcpWell.getBoundingBox().top)
272 ppowerMetal.setBottom(pEncMcpWell.getBoundingBox().bottom)
273
274 # now wire up everything
275 if npowerMetal.getBoundingBox().right < nsourceContact.getBoundingBox().left : # npowerMetal is in the left of nsourceContact
276     npowerSourceMetal = Rect(Layer("metal"), Box(npowerMetal.getBoundingBox().right, nsourceContact.getBoundingBox().bottom, nsourceContact

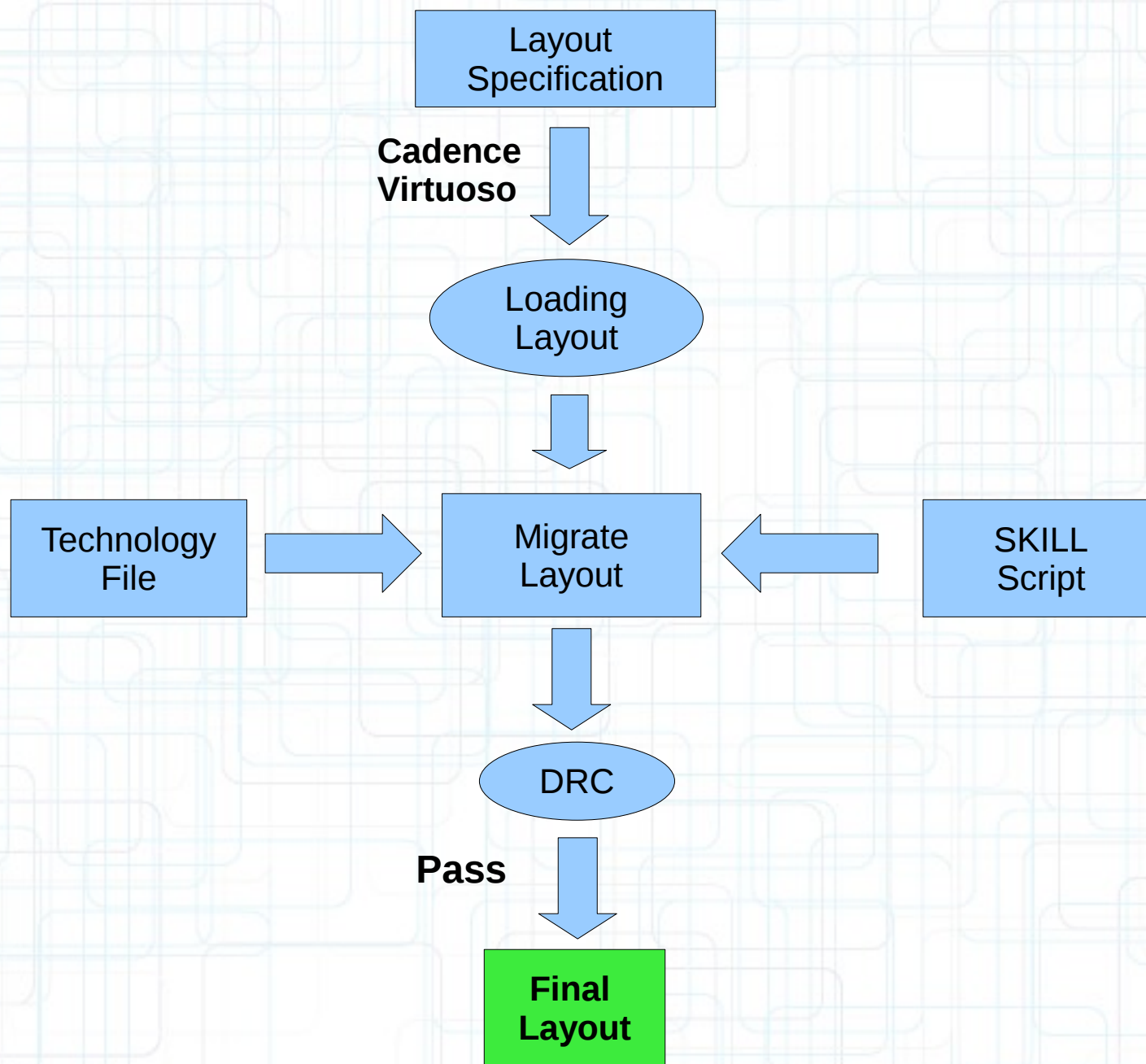
```

## Cons

- Every rule must be accounted for
- Newly developed technology may not be accounted for
- Heavy scripting (e.g.: 300 lines for an inverter)

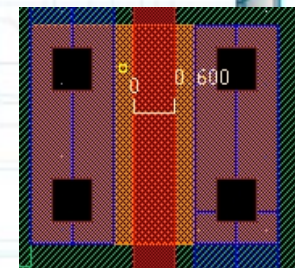
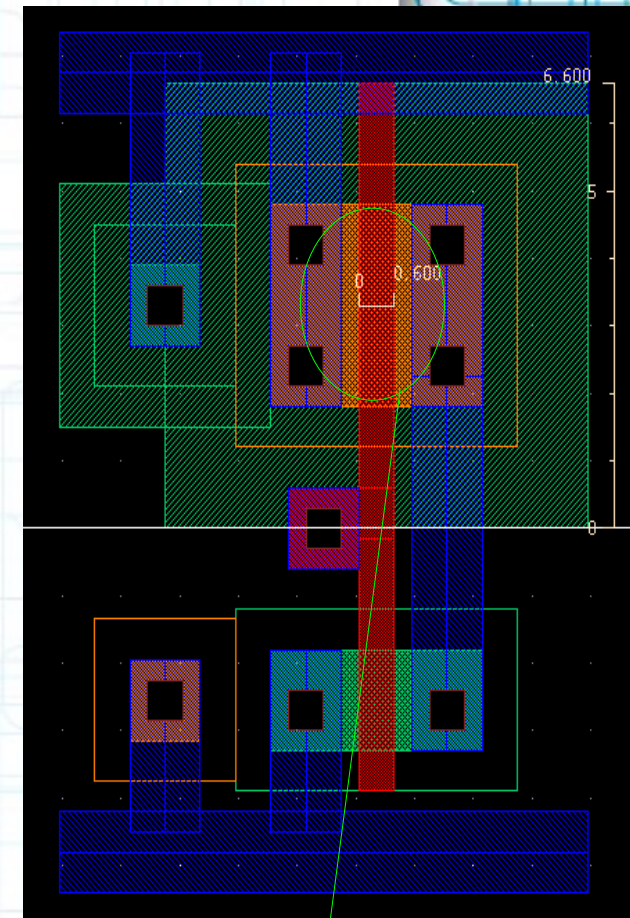
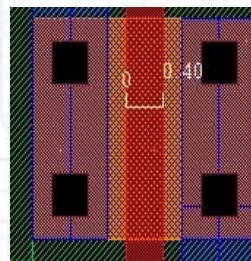
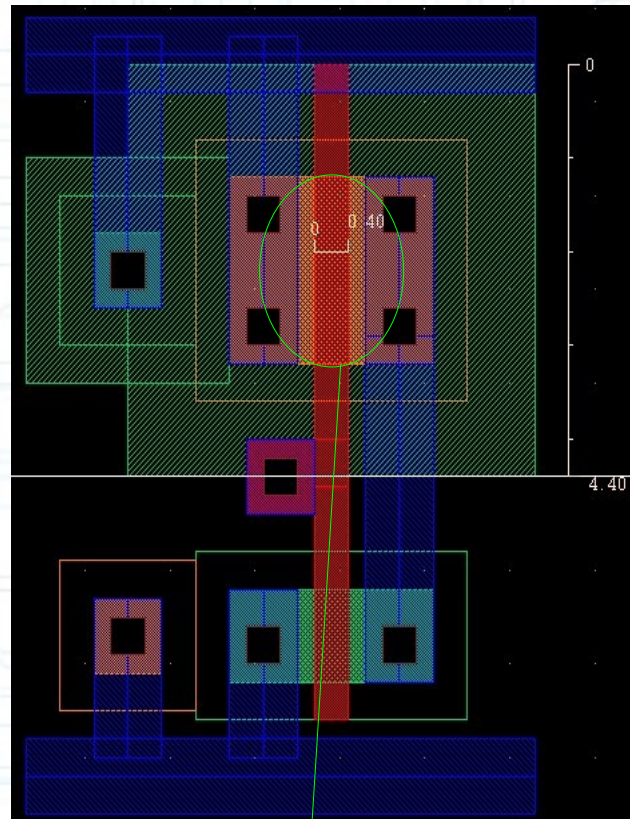
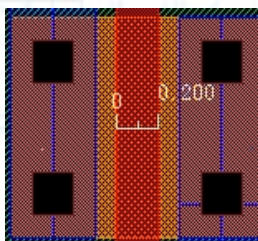
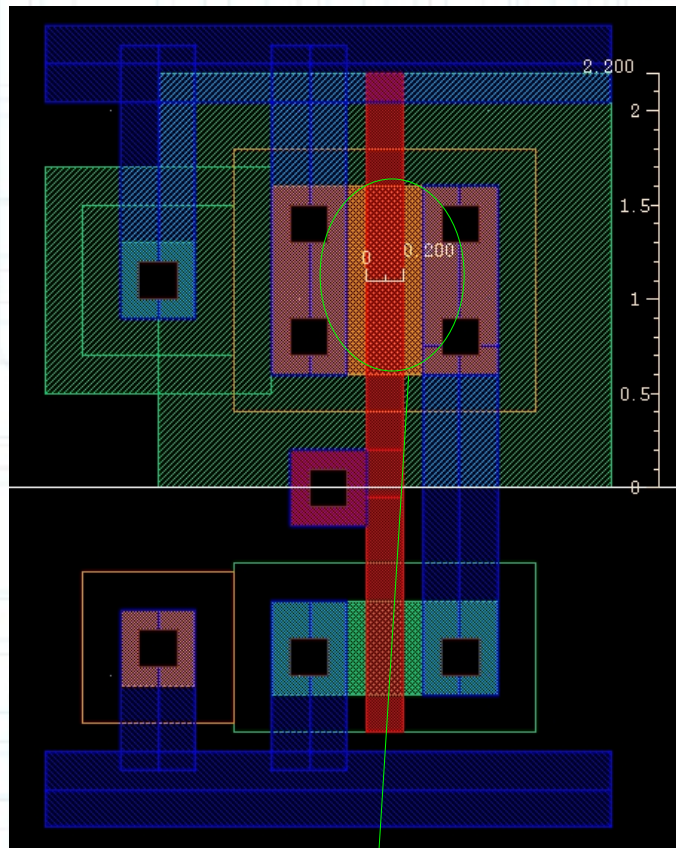
# Cadence SKILL: Methodology 1

## Quality By Design (QbD)



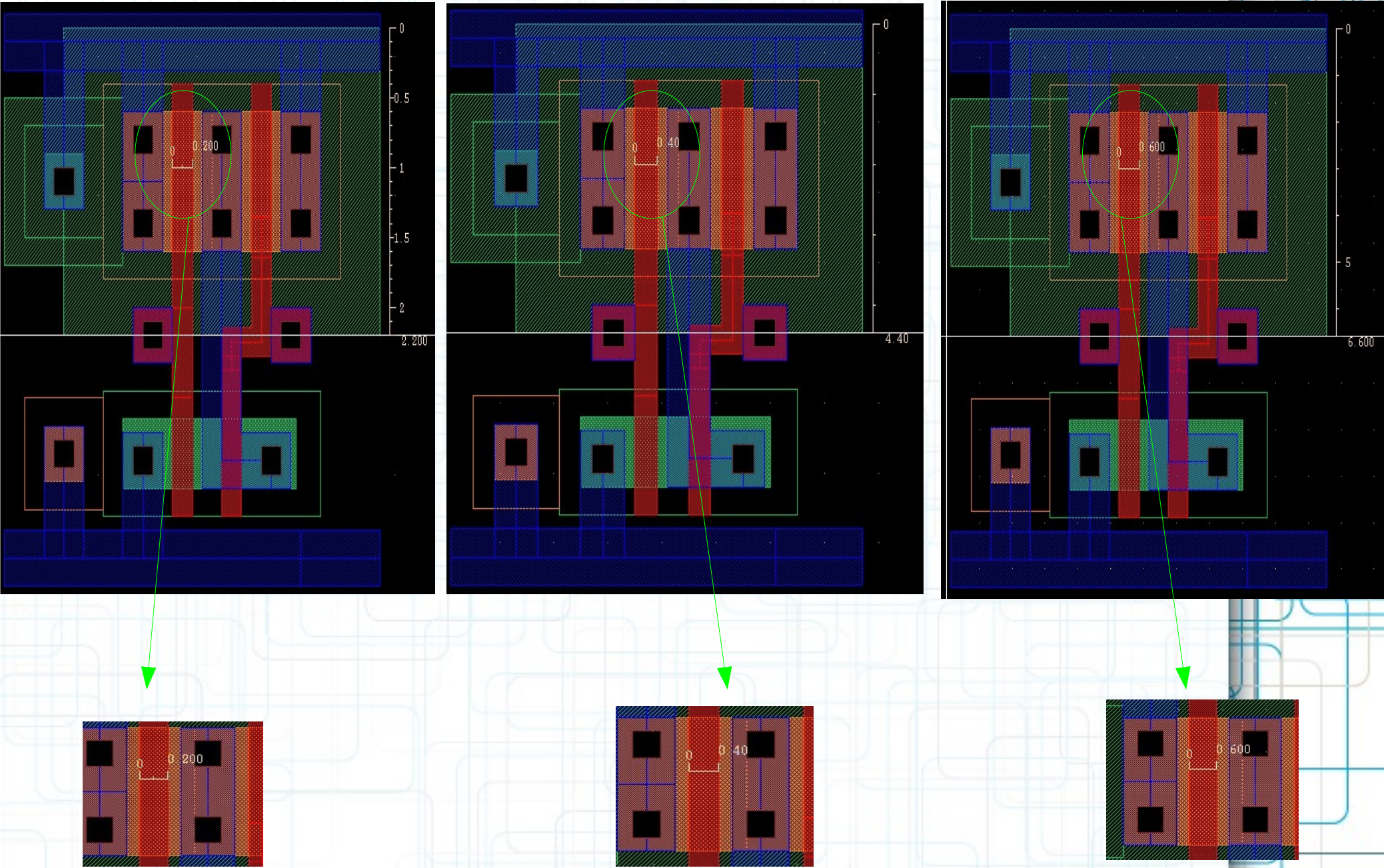


# Cadence SKILL: Inverter



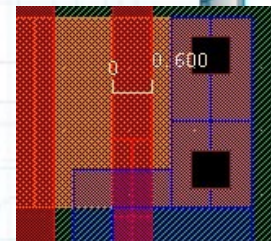
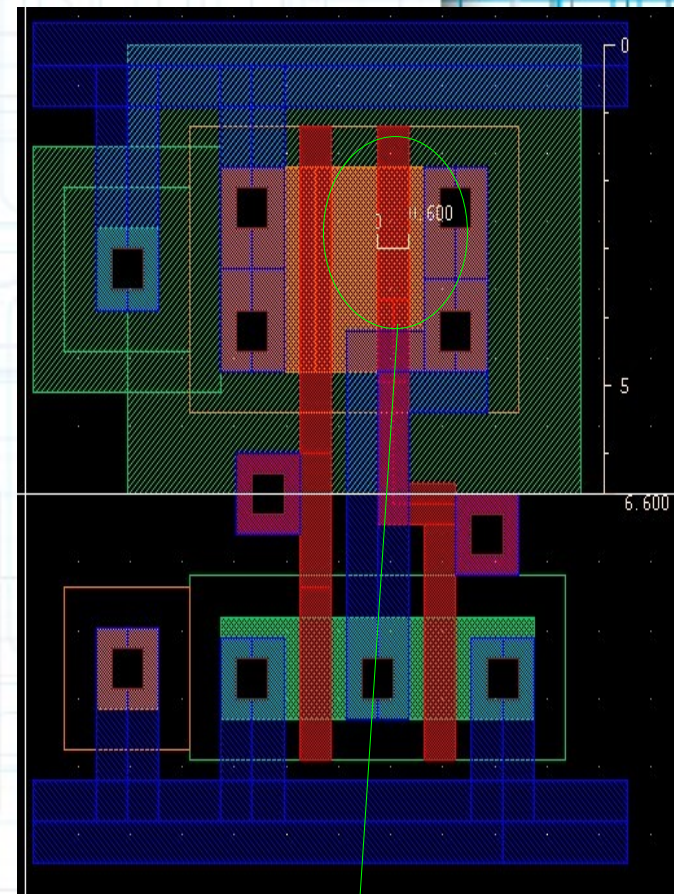
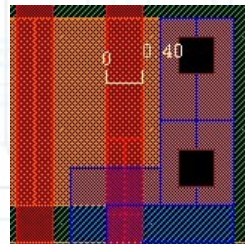
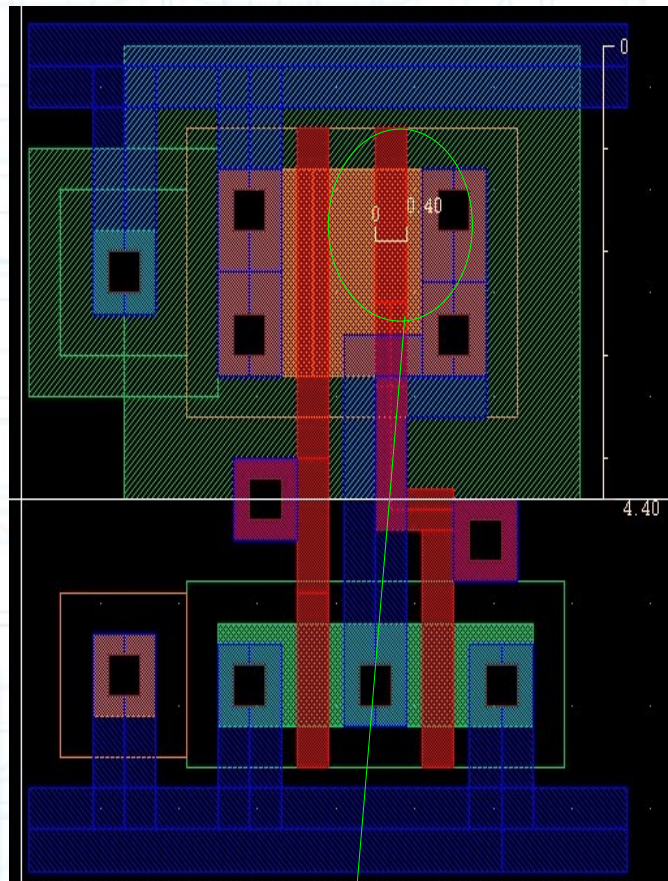
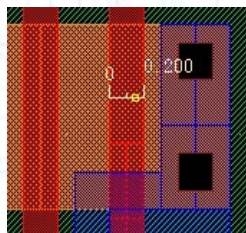
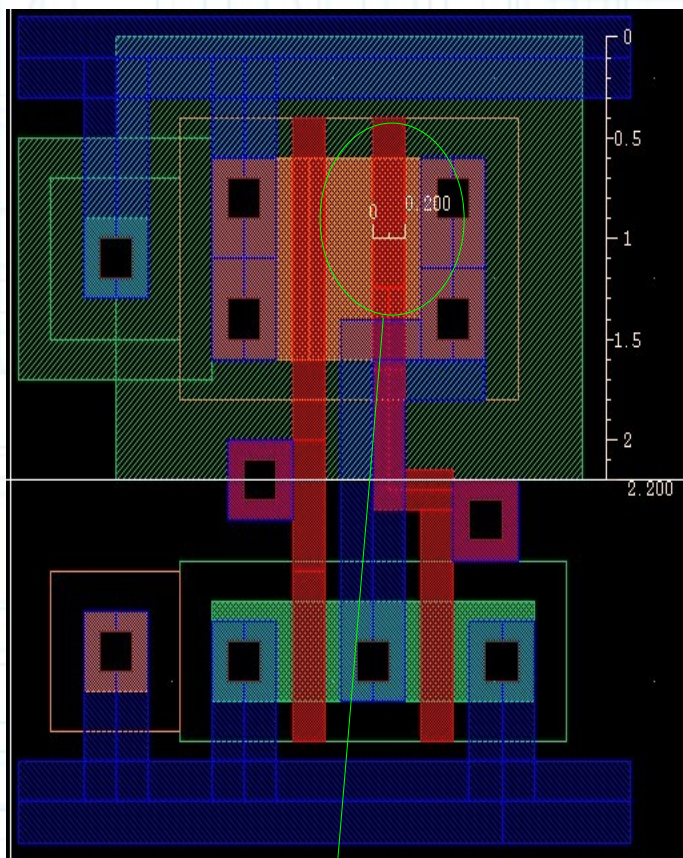


# Cadence SKILL: NAND





# Cadence SKILL: NOR

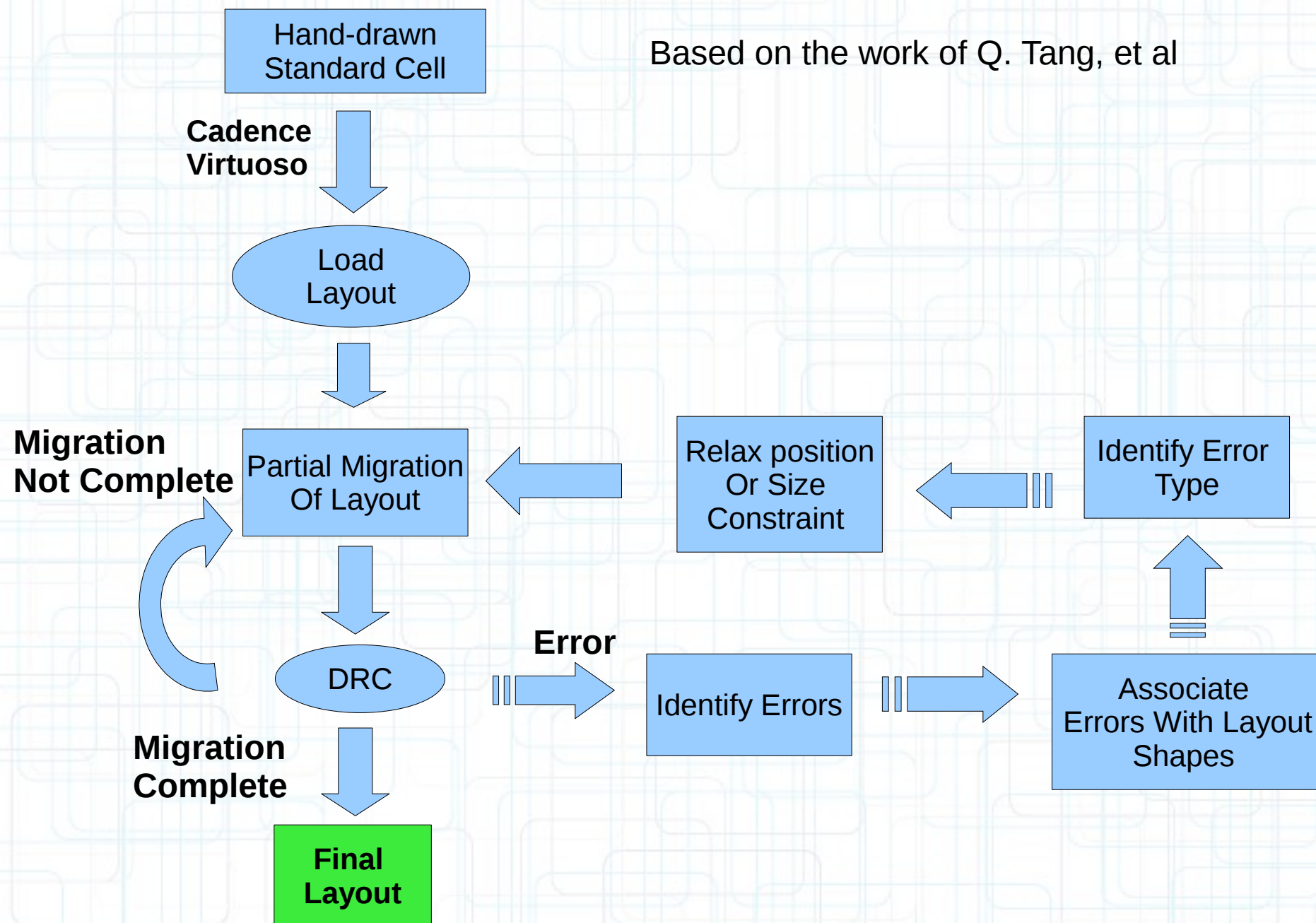




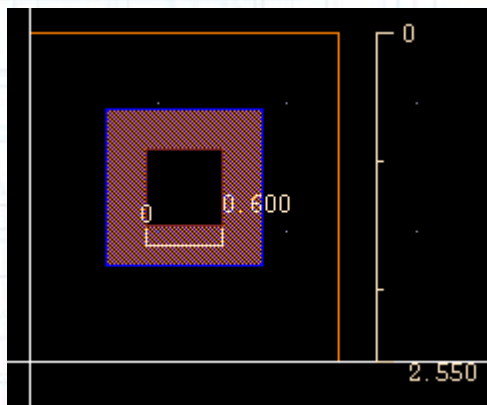
# Cadence SKILL: Methodology 2

## Adaptive Migration and Constraint Relaxation

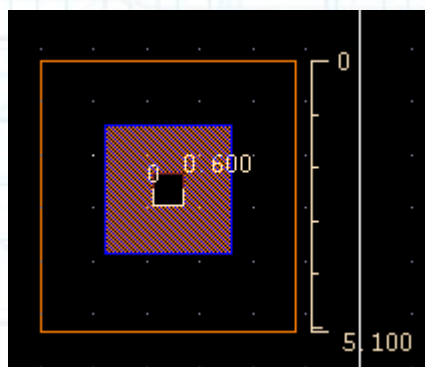
Based on the work of Q. Tang, et al



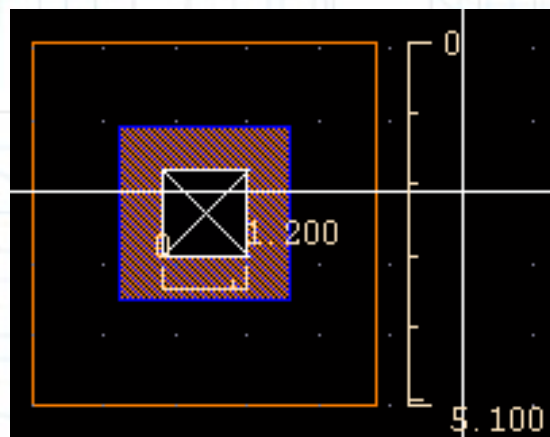
# Adaptive Migration



P-Tap 0.6ami



P-Tap Simulated Technology Migration, Adaptive. Error resolved



P-Tap Simulated Technology Migration, Non-Adaptive. Error: Via must be 0.6um square.



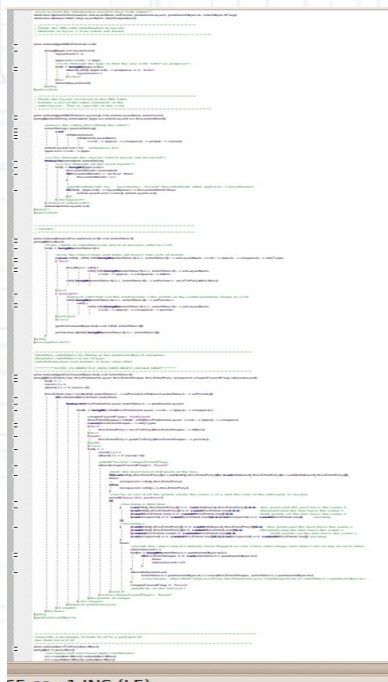
# Adaptive Migration: Pros & Cons

## Pros

- Requires no additional work.
- Mature literature on the subject.
- Adapts to new design rule requirements
- Same approach may be used for optimization.
- Built in SKILL functions (Not used here).

## Cons

- Adaptive is very complex.
- Large up front development.





# Evaluation: Comparison of Tools

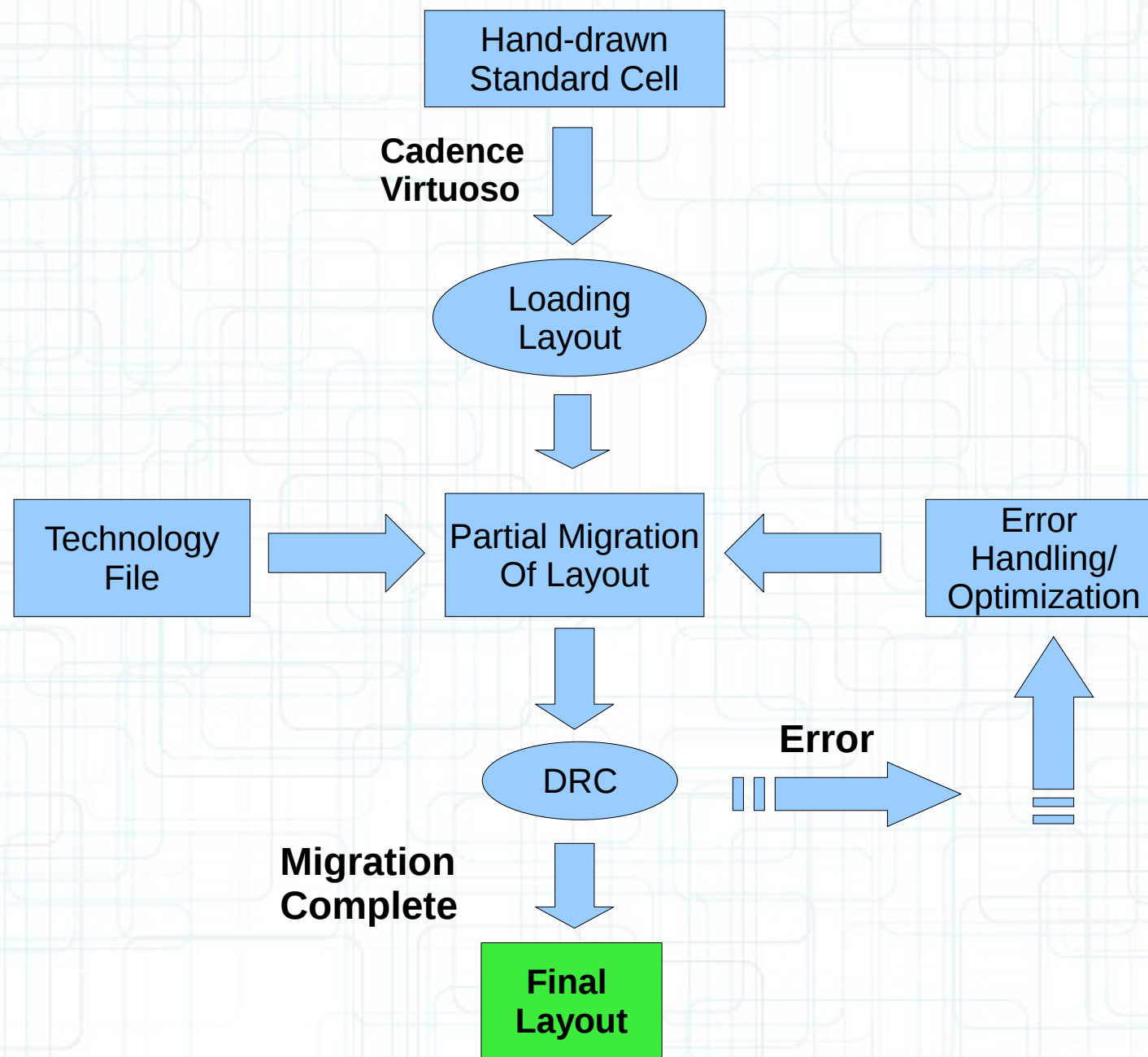
	<b>PyCell Studio</b>	<b>Cadence SKILL</b>
<b>Scripting Language</b>	Python	SKILL (LISP-like)
<b>Cost</b>	Free to use but pay to get commercial support	Pay to use and get commercial support
<b>Extension</b>	Almost none, have to interface with 3 <sup>rd</sup> party	Good
<b>Community support</b>	Almost none	Good
<b>Emphasis</b>	Parameterized cell	Generic
<b>Database</b>	Open Access database	CDS Start supporting OA

\* Cadence has a toolbox of doing layout compaction

**Cadence is a better candidate**

# Evaluation: Methodology Recommendation

## QbD with Adaptive Migration and Constraint Relaxation



# Summary

- ◆ The motivation of this project
- ◆ Two tools: PyCell and Cadence SKILL
- ◆ Different approaches
- ◆ Evaluation



**THANKS !**

**QUESTIONS ?**